Distributed Systems

21. Other parallel big data frameworks

Paul Krzyzanowski
Rutgers University
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MapReduce isn’t always the answer

• MapReduce works well for certain problems
  – Framework provides
    • Automatic parallelization
    • Automatic job distribution

• For others:
  – May require many iterations
  – Data locality usually not preserved between Map and Reduce
    • Lots of communication between map and reduce workers
Bulk Synchronous Parallel (BSP)

Computing model for parallel computation

• Series of supersteps
  1. Concurrent computation
  2. Communication
  3. Barrier synchronization
Bulk Synchronous Parallel (BSP)
Bulk Synchronous Parallel (BSP)

Series of supersteps
1. Concurrent computation
2. Communication
3. Barrier synchronization

- Processes (workers) are randomly assigned to processors
- Each process uses only local data
- Each computation is asynchronous of other concurrent computation
- Computation time may vary

Superstep 0
Superstep 1
Bulk Synchronous Parallel (BSP)

Series of supersteps
1. Concurrent computation
2. Communication
3. Barrier synchronization

- Messaging is restricted to the end of a computation superstep
- Each worker sends a message to 0 or more workers
- These messages are inputs for the next superstep
Bulk Synchronous Parallel (BSP)

Series of supersteps
1. Concurrent computation
2. Communication
3. Barrier synchronization

- The next superstep does not begin until all messages have been received
- Barriers ensure no deadlock: no circular dependency can be created
- Provide an opportunity to checkpoint results for fault tolerance
  - If failure, restart computation from last superstep
BSP Implementation: Apache Hama

• Hama: BSP framework on top of HDFS
  – Provides automatic parallelization & distribution
  – Uses Hadoop RPC
    • Data is serialized with Google Protocol Buffers
  – Zookeeper for coordination (Apache version of Google’s Chubby)
    • Handles notifications for Barrier Sync

• Good for applications with data locality
  – Matrices and graphs
  – Algorithms that require a lot of iterations

hama.apache.org
Hama programming (high-level)

• Pre-processing
  – Define the number of peers for the job
  – Split initial inputs for each of the peers to run their supersteps
  – Framework assigns a unique ID to each worker (peer)

• Superstep: the worker function is a superstep
  – `getCurrentMessage()` – input messages from previous superstep
  – Compute – your code
  – `send(peer, msg)` – send messages to a peer
  – `sync()` – synchronize with other peers (barrier)

• File I/O
  – Key/value model used by Hadoop MapReduce & HBase
    – `readNext(key, value)`
    – `write(key, value)`
For more information

• Architecture, examples, API

• Take a look at:
  – Apache Hama project page
    • http://hama.apache.org
  – Hama BSP tutorial
    • https://hama.apache.org/hama_bsp_tutorial.html
  – Apache Hama Programming document
    • http://bit.ly/1aiFbXS
Graph computing
Graphs are common in computing

- Social links
  - Friends
  - Academic citations
  - Music
  - Movies
- Web pages
- Network connectivity
- Roads
- Disease outbreaks
Processing graphs on a large scale is hard

- **Computation with graphs**
  - Poor locality of memory access
  - Little work per vertex

- **Distribution across machines**
  - Communication complexity
  - Failure concerns

- **Solutions**
  - Application-specific, custom solutions
  - MapReduce or databases
    - But require many iterations (and a lot of data movement)
  - Single-computer libraries: **limits scale**
  - Parallel libraries: **do not address fault tolerance**
  - BSP: **close** but too general
Pregel: a vertex-centric BSP

Input: directed graph
- A vertex is an object
  - Each vertex uniquely identified with a name
  - Each vertex has a modifiable value
- Directed edges: links to other objects
  - Associated with source vertex
  - Each edge has a modifiable value
  - Each edge has a target vertex identifier

http://googleresearch.blogspot.com/2009/06/large-scale-graph-computing-at-google.html
Computation: series of supersteps

- Same user-defined function runs on each vertex
  - Receives messages sent from the previous superstep
  - May modify the state of the vertex or of its outgoing edges
  - Sends messages that will be received in the next superstep
    - Typically to outgoing edges
    - But can be sent to any known vertex
  - May modify the graph topology

- Each superstep ends with a barrier (synchronization point)
Pregel terminates when every vertex votes to halt

• Initially, every vertex is in an **active** state
  – Active vertices compute during a superstep

• Each vertex may choose to deactivate itself by **voting to halt**
  – The vertex has no more work to do
  – Will not be executed by Pregel
  – **UNLESS** the vertex receives a message
    • Then it is reactivated
    • Will stay active until it votes to halt again

• Algorithm terminates when all vertices are inactive and there are no messages in transit
Pregel: output

• Output is the set of values output by the vertices
• Often a directed graph
  – May be non-isomorphic to original since edges & vertices can be added or deleted
• Or may be summary data
Examples of graph computations

• **Shortest path to a node**
  – Each iteration, a node sends the shortest distance received to all neighbors

• **Cluster identification**
  – Each iteration: get info about clusters from neighbors
  – Add myself
  – Pass useful clusters to neighbors (e.g., within a certain depth or size)
    • May combine related vertices
    • Output is a smaller set of disconnected vertices representing clusters of interest

• **Graph mining**
  – Traverse a graph and accumulate global statistics

• **Page rank**
  – Each iteration: update web page ranks based on messages from incoming links.
Simple example: find the maximum value

• Each vertex contains a value

• In the first superstep:
  – A vertex sends its value to its neighbors

• In each successive superstep:
  – If a vertex learned of a larger value from its incoming messages, it sends it to its neighbors
  – Otherwise, it votes to halt

• Eventually, all vertices get the largest value

• When no vertices change in a superstep, the algorithm terminates
Simple example: find the maximum value

Semi-pseudocode:

```cpp
class MaxValueVertex : public Vertex<int, void, int> {
    void Compute(MessageIterator *msgs) {
        int maxv = GetValue();
        for (; !msgs->Done(); msgs->Next())
            maxv = max(msgs.Value(), maxv);

        if (maxv > GetValue()) || (step == 0)) {
            *MutableValue() = maxv;
            OutEdgeIterator out = GetOutEdgeIterator();
            for (; !out.Done(); out.Next())
                sendMessageTo(out.Target(), maxv);
        } else
            VoteToHalt();
    }
};
```

1. vertex value type; 2. edge value type (none!); 3. message value type

- find maximum value
- send maximum value to all edges
Simple example: find the maximum value

Superstep 0: Each vertex propagates its own value to connected vertices

Superstep 1: $V_0$ updates its value: $6 > 3$
$V_3$ updates its value: $6 > 1$
$V_1$ and $V_2$ do not update so vote to halt
Simple example: find the maximum value

Superstep 0

Superstep 1

Superstep 2

Superstep 2: $V_1$ receives a message – becomes active
$V_3$ updates its value: $6 > 2$
$V_1$, $V_2$, and $V_3$ do not update so vote to halt
Simple example: find the maximum value

Superstep 2

Superstep 3: $V_1$ receives a message – becomes active
$V_3$ receives a message – becomes active
No vertices update their value – all vote to halt

Done!

Active vertex  Inactive vertex
Locality

• Vertices and edges remain on the machine that does the computation

• To run the same algorithm in MapReduce
  – Requires chaining multiple MapReduce operations
  – Entire graph state must be passed from Map to Reduce
    … and again as input to the next Map
Pregel API: Basic operations

- A user subclasses a Vertex class

- Methods
  - **Compute** (MessageIterator*): Executed per active vertex in each superstep
    - MessageIterator identifies incoming messages from previous supersteps
  - **GetValue()**: Get the current value of the vertex
  - **MutableValue()**: Set the value of the vertex
  - **GetOutEdgeIterator()**: Get a list of outgoing edges
    - .Target(): identify target vertex on an edge
    - .GetValue(): get the value of the edge
    - .MutableValue(): set the value of the edge
  - **SendMessageTo()**: send a message to a vertex
    - Any number of messages can be sent
    - Ordering among messages is not guaranteed
    - A message can be sent to *any* vertex (but our vertex needs to have its ID)
Combiners

- Each message has an overhead – let’s reduce # of messages
  - Many vertices are processed per worker (multi-threaded)
  - Pregel can combine messages targeted to one vertex into one message
- Combiners are application specific
  - Programmer subclasses a Combiner class and overrides Combine() method
- No guarantee on which messages may be combined
Aggregators

• Handle global data

• A vertex can provide a value to an aggregator during a superstep
  – Aggregator combines received values to one value
  – Value is available to all vertices in the next superstep

• User subclasses an Aggregator class

• Examples
  – Keep track of total edges in a graph
  – Generate histograms of graph statistics
  – Global flags: execute until some global condition is satisfied
  – Election: find the minimum or maximum vertex
Pregel API: Advanced operations

Topology modification

• Examples
  – If we’re computing a spanning tree: remove unneeded edges
  – If we’re clustering: combine vertices into one vertex

• Add/remove edges/vertices

• Modifications visible in the next superstep
Pregel Design
Execution environment

- Many copies of the program are started on a cluster of machines

- One copy becomes the master
  - Will not be assigned a portion of the graph
  - Responsible for coordination

- Cluster’s name server = chubby
  - Master registers itself with the name service
  - Workers contact the name service to find the master
Partition assignment

- **Master**
  - Determines # partitions in graph
  - One or more partitions assigned to each worker
    - Partition = set of vertices
    - Default: for $N$ partitions
      \[
      \text{hash(vertex ID)} \mod N \Rightarrow \text{worker}
      \]
      
      May deviate: e.g., place vertices representing the same web site in one partition
    - More than 1 partition per worker: improves load balancing

- **Worker**
  - Responsible for its section(s) of the graph
  - Each worker knows the vertex assignments of other workers
Input assignment

• Master assigns parts of the input to each worker
  – Data usually sits in GFS or Bigtable

• Input = set of records
  – Record = vertex data and edges
  – Assignment based on file boundaries

• Worker reads input
  – If it belongs to any of the vertices it manages, messages sent locally
  – Else worker sends messages to remote workers

• After data is loaded, all vertices are active
Computation

• Master tells each worker to perform a superstep

• Worker:
  – Iterates through vertices (one thread per partition)
  – Calls `Compute()` method for each active vertex
  – Delivers messages from the previous superstep
  – Outgoing messages
    • Sent asynchronously
    • Delivered before the end of the superstep

• When done
  – worker tells master how many vertices will be active in the next superstep

• Computation done when no more active vertices in the cluster
  – Master may instruct workers to save their portion of the graph
Handling failure

• **Checkpointing**
  – Controlled by master … every $N$ supersteps
  – Master asks a worker to checkpoint at the start of a superstep
    • Save state of partitions to persistent storage
      – Vertex values
      – Edge values
      – Incoming messages
  – Master is responsible for saving aggregator values

• **Failure detection**: master sends *ping* messages to workers
  – If worker does not receive a ping within a time period
    ⇒ Worker terminates
  – If the master does not hear from a worker
    ⇒ Master marks worker as failed

• **Restart**: when failure is detected
  – Master reassigns partitions to the current set of workers
  – **All** workers reload partition state from most recent checkpoint
Apache Giraph

– Initially created at Yahoo
– Used at LinkedIn & Facebook to analyze the social graphs of users
  • Facebook is the main contributor to Giraph
  • Facebook analyzed 1 trillion edges via 200 machines in 4 minutes
– Runs under Hadoop MapReduce framework
  • Runs as a \textit{Map}-only job
  • Adds fault-tolerance to the master by using ZooKeeper for coordination
  • Uses Java instead of C++

\text{= Chubby}

https://www.facebook.com/notes/facebook-engineering/scaling-apache-giraph-to-a-trillion-edges/10151617006153920
Conclusion

Vertex-centric approach to BSP

• Computation = set of supersteps
  – Compute() called on each vertex per superstep
  – Communication between supersteps: barrier synchronization

• Hides distribution from the programmer
  – Framework creates lots of workers
  – Distributes partitions among workers
  – Distributes input
  – Handles message sending, receipt, and synchronization
  – A programmer just has to think from the viewpoint of a vertex

• Checkpoint-based fault tolerance
Can we make MapReduce easier?
Apache Hive

• MapReduce is powerful but requires
  – Java programming
  – Parsing of input data
  – Programmers to figure out whether multiple iterations are needed

• Apache Hive offers
  – HiveQL: a query language similar to SQL
  – Table structure for data
  – Compiler that handles parsing, filtering, joining, etc., and
    scheduling multiple MapReduce jobs
  – Lots of user-defined functions (extensible)
Hive Components

- **Metastore**
  - Stores metadata for each of the tables
  - Tables are stored as HDFS files or externally

- **User interface**
  - Various clients: web client, command-line interface, JDBC/ODBC

- **Driver**
  - Receives HiveQL statements & creates sessions to execute them
  - Monitors progress & collects results from *reduce*

- **Compiler & Optimizer**
  - HiveQL → Directed Acyclic Graph (DAG)
  - Create optimized set of operations for MapReduce

- **Execution Engine**
  - Takes optimized DAG and runs the needed MapReduce jobs
Apache Hive Flow

Hadoop

MapReduce
Job Tracker

NameNode

DataNodes

DataNodes

Web UI

Client program
Client Driver
Command-Line Interface

Driver
Compiler
Optimizer

Execution Engine
Metastore

Client program

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1. The query is delivered to the driver.
2. Driver creates a session for the query.
3. The compiler parses the query. It contacts the metastore info about the data & generates an execution plan.
4. The execution plan is sent to the driver.
5. The driver sends the execution plan to the Execution Engine.
6. The Execution Engine sends the jobs to MapReduce.
7. The execution engine tells the driver the job is done and reads any results from the HDFS data nodes.
8. Results are sent back to the user interface.
Hive summary

• Designed as a data warehouse tool

• Not a relational database or on-line transaction processing (OLTP) system
  – No row-level data updates
  – No concept of transactions
  – No real-time queries (they are MapReduce jobs)
    • But usually fast enough for interactive use

• Benefits
  – Makes it easy to treat huge collections of data as a database
  – Easy to create & submit queries
    • No need to know Java or MapReduce
Spark: Generalizing MapReduce
MapReduce problems

• Not efficient when multiple passes needed
• Problems need to be converted to a series of Map & Reduce operations
  
  ![MapReduce Diagram]

  - Map → Reduce → Map → Reduce → Map → Reduce

• The next phase can never start until the previous has completed
• Output needs to be stored in the file system before the next step starts
• Storage involves disk writes & replication
Apache Spark Goals

• Generalize MapReduce
  – Similar shard-and-gather approach to MapReduce
  – Create multi-step pipelines based on directed acyclic graphs (DAGs) of data flows

• Create a general functional programming model
  – *Transformation* and *action*
  – In Map-Reduce, *transformation* = *map*, *action* = *reduce*
  – Support operations beyond *map* and *reduce*

• Add fast data sharing
  – In-memory caching
  – Different computation phases can use the same data if needed

• And generic data storage interfaces
  – Storage agnostic: use HDFS, Cassandra database, whatever
  – Resilient Distributed Data (RDD) sets
    • An RDD is a chunk of data that gets processed – a large collection of stuff
Spark Design: RDDs

RDD: Resilient Distributed Datasets
- Table that can be sharded across many servers
- Holds any type of data
- Immutable: you can process the RDD to create a new RDD but not modify the original

Two operations on RDDs
1. **Transformations**: transformation function takes RDD as input & creates a new RDD
   - Examples: `map`, `filter`, `flatMap`, `groupByKey`, `reduceByKey`, `aggregateByKey`, ...

2. **Actions**: evaluates an RDD and creates a value:
   - Examples: `reduce`, `collect`, `count`, `first`, `take`, `countByKey`, ...

• Shared variables
  - **Broadcast Variables**: define read-only data that will be cached on each system
  - **Accumulators**: used for counters (e.g., in MapReduce) or sums
    - Only the driver program can read the value of the accumulator.
High-level view

- **Job** = bunch of transformations & actions on RDDs
High-level view

- Cluster manager breaks the job into tasks
- Sends tasks to worker nodes where the data lives
Worker node

One or more **executors**

- JVM process
- Talks with cluster manager
- Receives **tasks**
  - JVM code (e.g., compiled Java, Clojure, Scala, JRuby, …)
  - Task = **transformation** or **action**
- Data to be processed (RDD)
- Cache
  - Stores results in memory
  - Key to high performance

![Diagram of worker node and cluster manager interactions](image)
Worker node

One or more **executors**

- Separate JVM process
- Talks with cluster manager
- Receives **tasks**
  - JVM code (e.g., compiled Java, Clojure, Scala, JRuby, …)
  - Task = **transformation** or **action**
- Data to be processed (RDD)
  - Try to run tasks close to data
- Cache
  - Stores results in memory
  - Key to high performance
• Data organized into RDDs
  – One RDD may be partitioned across lots of computers

• How are RDDs created?
  1. Create from any file stored in HDFS or other storage supported in Hadoop (Amazon S3, HDFS, HBase, Cassandra, etc.)
     • Created externally (e.g., event stream, text files, database)
     • Example:
       – Query a database & make the query results an RDD
       – Any Hadoop InputFormat, such as a list of files or a directory
  2. Streaming sources (via Spark Streaming)
     • Fault-tolerant stream with a sliding window
  3. Output of a Spark transformation function
     • Example, filter out data, select key-value pairs
Properties of RDDs

• **Immutable**
  – You cannot change it – only create new RDDs
  – The framework will eventually collect unused RDDs

• **Partitioned** – parts of an RDD may go to different servers
  – Splits can be range-based or hash-based
  – For hash-based, default partitioning function = \( \text{hash(key)} \mod \text{server_count} \)

• Created from – and thus **dependent** on other RDDs
  – Either original source data or computed from one or more other RDDs

• **Fault tolerant**
  – Original RDD in stable storage; other RDDs can be regenerated if needed

• **Persistent** – optional for intermediate RDDs
  – Original data is persistent. Intermediate data can be marked to be persistent

• **Typed**
  – Contains some parsable data structure – e.g., key-value set

• **Ordered** (optional)
  – Elements in an RDD can be sorted
Operations on RDDs

Two types of operations on RDDs

• **Transformations**: create new RDDs
  – Lazy: computed when needed, not immediately
  – Transformed RDD is computed when an action is run on it
    • Work backwards:
      – What RDDs do you need to apply to get an action?
      – What RDDs do you need to apply to get the input to this RDD?
  – RDD can be persisted into memory or disk storage

• **Actions**: create result values
  – Finalizing operations
    • *Reduce, count, grab samples, write to file*
<table>
<thead>
<tr>
<th>Transformation</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>map</strong> (func)</td>
<td>Pass each element through a function <em>func</em></td>
</tr>
<tr>
<td><strong>filter</strong> (func)</td>
<td>Select elements of the source on which <em>func</em> returns true</td>
</tr>
<tr>
<td><strong>flatMap</strong> (func)</td>
<td>Each input item can be mapped to 0 or more output items</td>
</tr>
<tr>
<td><strong>sample</strong> (withReplacement, fraction, seed)</td>
<td>Sample a <em>fraction</em> fraction of the data, with or without replacement, using a given random number generator seed</td>
</tr>
<tr>
<td><strong>union</strong> (otherdataset)</td>
<td>Union of the elements in the source data set and <em>otherdataset</em></td>
</tr>
<tr>
<td><strong>intersection</strong> (otherdataset)</td>
<td>The elements that are in common to two datasets</td>
</tr>
</tbody>
</table>
## Spark Transformations

<table>
<thead>
<tr>
<th>Transformation</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>groupByKey([numtasks])</code></td>
<td>When called on a dataset of (K, V) pairs, returns a dataset of (K, seq[V]) pairs</td>
</tr>
<tr>
<td><code>reduceByKey(func, [numtasks])</code></td>
<td>Aggregate the values for each key using the given reduce function</td>
</tr>
<tr>
<td><code>sortByKey([ascending], [numtasks])</code></td>
<td>Sort keys in ascending or descending order</td>
</tr>
<tr>
<td><code>join(otherDataset, [numtasks])</code></td>
<td>Combines two datasets, (K, V) and (K, W) into (K, (V, W))</td>
</tr>
<tr>
<td><code>cogroup(otherDataset, [numtasks])</code></td>
<td>Given (K, V) and (K, W), returns (K, Seq[V], Seq[W])</td>
</tr>
<tr>
<td><code>cartesian(otherDataset)</code></td>
<td>For two datasets of types T and U, returns a dataset of (T, U) pairs</td>
</tr>
</tbody>
</table>
# Spark Actions

<table>
<thead>
<tr>
<th>Action</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>reduce(func)</td>
<td>Aggregate elements of the dataset using <code>func</code>.</td>
</tr>
<tr>
<td>collect(func, [numtasks])</td>
<td>Return all elements of the dataset as an array</td>
</tr>
<tr>
<td>count()</td>
<td>Return the number of elements in the dataset</td>
</tr>
<tr>
<td>first()</td>
<td>Return the first element of the dataset</td>
</tr>
<tr>
<td>take(n)</td>
<td>Return an array with the first <code>n</code> elements of the dataset</td>
</tr>
<tr>
<td>takeSample(withReplacement, fraction, seed)</td>
<td>Return an array with a random sample of <code>num</code> elements of the dataset</td>
</tr>
</tbody>
</table>
# Spark Actions

<table>
<thead>
<tr>
<th>Action</th>
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</tr>
</thead>
<tbody>
<tr>
<td><code>saveAsTextFile(path)</code></td>
<td>Write dataset elements as a text file</td>
</tr>
<tr>
<td><code>saveAsSequenceFile(path)</code></td>
<td>Write dataset elements as a Hadoop SequenceFile</td>
</tr>
<tr>
<td><code>countByKey()</code></td>
<td>For (K, V) RDDs, return a map of (K, Int) pairs with the count of each key</td>
</tr>
<tr>
<td><code>foreach(func)</code></td>
<td>Run <code>func</code> on each element of the dataset</td>
</tr>
</tbody>
</table>
Data Storage

• Spark does not care how source data is stored
  – RDD connector determines that
  – E.g.,
    read RDDs from tables in a Cassandra DB;
    write new RDDs to HBase tables

• RDD Fault tolerance
  – RDDs track the sequence of transformations used to create them
  – Enables recomputing of lost data
    • Go back to the previous RDD and apply the transforms again
    • Dependencies tracked by Spark in a **directed acyclic graph** (DAG)
Example: processing logs

• **Transform** *(creates new RDDs)*
  – Extract error message from a log
  – Parse out the source of error

• **Actions**: count mysql & php errors

```scala
// base RDD
val lines = sc.textFile("hdfs://...")

// transformed RDDs
val errors = lines.filter(_.startsWith("ERROR"))
val messages = errors.map(_.split("\t")).map(r => r(1))
messages.cache()

// action 1
messages.filter(_.contains("mysql")).count()

// action 2
messages.filter(_.contains("php")).count()
```
Spark Ecosystem

- **Spark Streaming**: process real-time streaming data
  - Micro-batch style of processing
  - Uses DStream: series of RDDs

- **Spark SQL**: access Spark data over JDBC API
  - Use SQL-like queries on Spark data

- **Spark Mlib**: machine learning library
  - Utilities for classification, regression, clustering, filtering, ...

- **Spark GraphX**: graph computation
  - Adds Pregel API to Spark
  - Extends RDD by introducing a directed multi-graph with properties attached to each vertex & edge.
  - Set of operators to create subgraphs, join vertices, aggregate messages, ...
Spark Streaming

- MapReduce & Pregel expect static data
- **Spark Streaming** enables processing live data streams
  - Same programming operations
  - Input data is chunked into batches
    - Programmer specifies time interval
Spark Streaming: DStreams

Discretized Stream = DStream

– Continuous stream of data (from source or a transformation)
– Appears as a continuous series of RDDs, each for a time interval

– Each operation on a DStream translates to operations on the RDDs

– Join operations allow combining multiple streams
Spark Summary

• Fast
  – Often up to 10x faster on disk and 100x faster in memory than MapReduce
  – General execution graph model
    • No need to have "useless" phases just to fit into the model
  – In-memory storage for RDDs

• Fault tolerant: RDDs can be regenerated
  – You know what the input data set was, what transformations were applied to it, and what output it creates

• Supports streaming
  – Handle continuous data streams via Spark Streaming
The end