

The Multilinear Minimax Relaxation of Bimatrix Games and Comparison with Nash Equilibria via Lemke-Howson

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- Balanced Scaling

Unit Simplex

For a positive integer k denote the unit simplex by

$$S_k = \{u \in \mathbb{R}^k : \sum_{j=1}^k u_j = 1, u \geq 0\}. \quad (1)$$

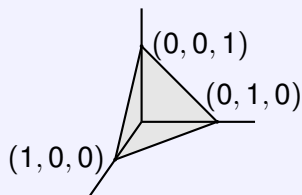


Figure: The unit simplex S_k .

Theorem

Let $A = (a_{ij})$ be an $m \times n$ real matrix.

$$\max_{x \in S_m} \min_{y \in S_n} x^T A y = \min_{y \in S_n} \max_{x \in S_m} x^T A y,$$

where S_k is the unit simplex in \mathbb{R}^k , i.e.

$$S_k = \{x \in \mathbb{R}^k : \sum_{i=1}^k x_i = 1, \quad x \geq 0\}.$$

Theorem

(Nash) Let $R = (R_{ij})$ and $C = (C_{ij})$ be $m \times n$ real payoff matrices. Given $p = (x, y) \in S_m \times S_n$, set

$$R[p] = x^T R y, \quad C[p] = x^T C y.$$

There exists a composite vector $p_* = (x_*, y_*)$ (called Nash Equilibrium) such that

$$\max\{R[p] : p = (x, y_*), x \in S_m\} = R[p_*]$$

and

$$\max\{C[p] : p = (x_*, y), y \in S_n\} = C[p_*].$$

Nash Equilibria - Non-Cooperative Games

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It is not known if p_* can be computed efficiently.

The Multilinear Minimax Relaxation (MMR) Theorem

Theorem

(Kalantari) Set $\Delta = S_m \times S_n$. Given $\alpha = (\alpha_1, \alpha_2) \in S_2$ and $p = (x, y) \in \Delta$, let

$$A_0[\alpha, p] = \alpha_1 R[p] + \alpha_2 C[p], \quad (2)$$

Then,

$$\min_{\alpha \in S_2} \max_{p \in \Delta} A_0[\alpha, p] = \max_{p \in \Delta} \min_{\alpha \in S_2} A_0[\alpha, p]. \quad (3)$$

Let α^* and $p^* = (x^*, y^*)$ be a minimax solution. Then, for any $(\alpha, p) \in S_2 \times \Delta$ we have

$$A_0[\alpha^*, p] \leq A_0[\alpha^*, p^*] \leq A_0[\alpha, p^*] \quad (4)$$

Furthermore, (α^*, p^*) is computable via a primal-dual pair of linear programming with $O(m \times n)$ variables. \square

A Game-Theoretic Interpretation of MMR

The game is played as a meta-player against *Row* and *Column*.

The meta-player chooses an $\alpha \in S_2$. *Row* chooses $x \in S_m$ and *Column* chooses $y \in S_n$.

Once α and $p = (x, y)$ are chosen, the meta-player's expected loss is $A_0[\alpha, p]$, while *Row* and *Column* gains the same amount.

Under pure strategies, the meta-player plays against either *Row* and *Column*.

Corollary

Let p_ be a Nash equilibrium and p^* a solution to MMR. Then*

$$\alpha_1^* R[p_*] + \alpha_2^* C[p_*] \leq \alpha_1^* R[p^*] + \alpha_2^* C[p^*].$$

In other words we can approximate a convex combination of R and C payoffs under Nash equilibrium.

Corollary

Either $R[p_] \leq R[p^*]$, or $C[p_*] \leq C[p^*]$. In particular, if both inequalities are satisfied, then p^* gives a better payoff than p_* for both players. \square*

The primal-dual LP formulation of MMR is the following:

$$\begin{aligned} & \min \delta \\ (LP) \quad & R_{ij}\alpha_1 + C_{ij}\alpha_2 \leq \delta, \quad \forall i \in [1, n], j \in [1, m], \\ & \alpha_1 + \alpha_2 = 1, \\ & \alpha_1 \geq 0, \\ & \alpha_2 \geq 0. \end{aligned}$$

$$\begin{aligned} & \max \lambda \\ (DLP) \quad & \sum_{i=1}^n \sum_{j=1}^m R_{ij} q_{ij} \geq \lambda, \\ & \sum_{i=1}^n \sum_{j=1}^m C_{ij} q_{ij} \geq \lambda, \\ & \sum_{i=1}^n \sum_{j=1}^m q_{ij} = 1, \\ & q_{ij} \geq 0, \quad \forall i \in [1, n], j \in [1, m]. \end{aligned}$$

Algorithmic Computation of MMR

Let Q be the $m \times n$ matrix (q_{ij}) . Given a positive integer k let $e_k = (1, \dots, 1)^T \in \mathbb{R}^k$. Then set

$$x^* = Qe_n \quad y^* = Q^T e_m.$$

Then x^* and y^* are the strategies for *Row* and *Column*.

Computational Results

Using Gambit 15.1.1, the entries of payoff matrices are generated randomly between 0 and 1.

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Programs run for a maximum time of 30 minutes before they are terminated and returned an error. For each comparison, we ran the algorithms 1000 times.

Computational Results

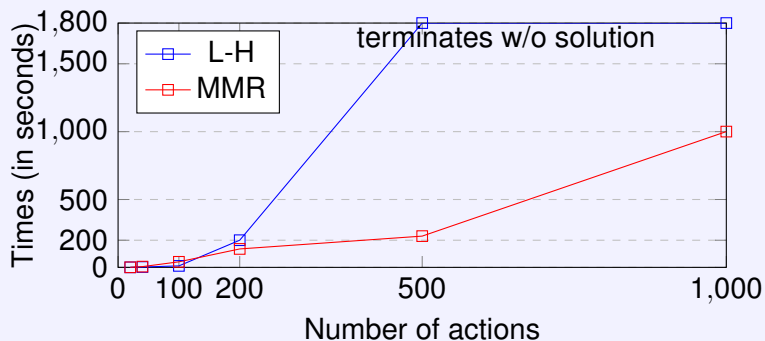


Figure: Speed comparisons for Lemke-Howson and MMR algorithms

Computational Results

Actions	Percentages
10	81.2%
30	80.3%
60	79.98%
100	82.0055%
150	80.023%

Figure: Percentages of times MMR algorithm had better payoffs for both players

Computational Results

Actions	Relative errors
10	$0.129 \pm .020$
30	$0.090 \pm .012$
60	$0.110 \pm .010$
100	$0.151 \pm .016$
150	$0.141 \pm .004$

Figure: Relative errors of payoffs if one player's MMR payoff did worse than the Nash equilibrium payoff

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Figure: Relative errors of payoffs if one player's MMR payoff did worse than the Nash equilibrium payoff

As shown by the experimental results, MMR algorithm outperforms Lemke-Howson both in speed and the quality of payoffs.

Balanced Scaling Theorem

Definition

A profile is called *balanced* if both expected payoffs are equal.

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Theorem

Given payoff matrices $R, C \in [0, 1]^{n \times n}$, for each $t \in [0, 1]$ let $p^*(t) = (p^{1*}(t), p^{2*}(t))$ be the MMR solution corresponding to the case when R is replaced by tR and C by $(1 - t)C$. Then there exists $t_* \in [0, 1]$ that gives a balanced scaling, i.e.

$$t_* R[p^*(t_*)] = (1 - t_*) C[p^*(t_*)], \quad (5)$$

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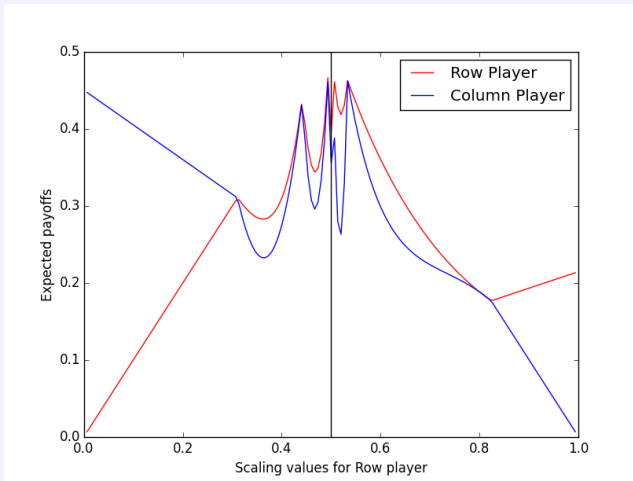
$$t_* R[p^*(t_*)] = (1 - t_*) C[p^*(t_*)], \quad (5)$$

To compute a convex scaling that gives balanced MMR payoffs, we can use the Bisection Method to change the value of t .

The advantage is that there exists a *convex* scaling pair $d = (t, 1 - t) \in S_2$ so that the MMR expected payoffs for *Row* and *Column* players are equal.

At least one player's expected payoff is at least as good as the expected payoffs of any Nash equilibria.

Visualizations of Balanced Scalings



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- In a good percentage of time, it out-performs Lemke-Howson in speed and in quality of solutions.
- Because Nash equilibria can be applied to machine-learning algorithms and robotics, we expect the applicability of MMR in such problems.

B. Kalantari, Approximating Nash Equilibrium Via Multilinear Minimax, arxiv.org/pdf/1605.00167.pdf, 2019.

B. Kalantari and C. L. Lau, The Multilinear Minimax Relaxation of Bimatrix Games and Comparison with Nash Equilibria Via Lemke-Howson, arxiv.org/pdf/1809.01717.pdf, 2019.

THANK YOU!