Adaptive Algorithms for Blind Separation of Dependent Sources

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Outline

- Problem definition–Motivation
- Existing adaptive scheme–Independence
- General adaptive scheme–Dependence
  - Imposing the desired limits
  - Imposing symmetric behavior
  - Non–separable sources
- Performance measure
- Optimum algorithms
- Conclusion
If the observation sequence $X(n)$ is available, estimate the source sequence $S(n)$. Equivalently, estimate $B = A^{-1}$.

Interested in adaptive techniques. At every time $n$, available $X(n)$ and form an estimate $B(n)$ of $A^{-1}$. 

\[
\begin{bmatrix}
    x_1(n) \\
    x_2(n) \\
    \vdots \\
    x_L(n)
\end{bmatrix} =
\begin{bmatrix}
    a_{11} & a_{12} & \cdots & a_{1L} \\
    a_{21} & a_{22} & \cdots & a_{2L} \\
    \vdots & \vdots & \ddots & \vdots \\
    a_{L1} & a_{L2} & \cdots & a_{LL}
\end{bmatrix}
\begin{bmatrix}
    s_1(n) \\
    s_2(n) \\
    \vdots \\
    s_L(n)
\end{bmatrix}
\]

$X(n) = AS(n)$
Why Dependent Sources?

- Because it is analytically challenging.
- Here is a “practical reason” to motivate such an analysis:

\[ f(s_1,\ldots,s_L) = 0.99 \prod_{i=1}^{L} f_i(s_i) + 0.01 \prod_{i=1}^{L} g_i(s_i) \]

\( \varepsilon \)-contamination model

\( f(s_1,\ldots,s_L) \) no longer corresponds to independent sources!!

**Question:** Do BSS algorithms still work under such mild divergence from the independence assumption?
Consider \( L = 2 \) sources and let \( B(n) \) denote the estimate of \( A^{-1} \) at time \( n \). At time \( n \) available: \( B(n-1), X(n) \)

\[
\hat{S}(n) = B(n - 1)X(n)
\]

\[
B(n) = B(n - 1) - \mu H\left(\hat{S}(n)\right)B(n - 1), \; B(0) = I
\]

\( \mu \) is a constant (step size) with \( 0 < \mu << 1 \).

\[
H(Z) = \begin{bmatrix}
z_1^2 - 1 & z_1 z_2 \\
z_1 z_2 & z_2^2 - 1
\end{bmatrix} + \begin{bmatrix}
0 & g_1(z_1)z_2 - g_2(z_2)z_1 \\
g_1(z_2)z_1 - g_2(z_1)z_2 & 0
\end{bmatrix}
\]

\( g_i(z) \) are odd univariate nonlinear function (i.e. \( g_i(-z) = -g_i(z) \)).
Acceptable solution(s)

\[ \hat{S}(n) = B(n - 1)X(n) = B(n - 1)AS(n) = C(n - 1)S(n) \]

\[ C(n) \rightarrow \begin{bmatrix} \pm c_1 & 0 \\ 0 & \pm c_2 \end{bmatrix} \quad \hat{S}(n) \rightarrow \begin{bmatrix} \pm c_1s_1(n) \\ \pm c_2s_2(n) \end{bmatrix} \]

\[ \rightarrow \begin{bmatrix} 0 & \pm c_2 \\ \pm c_1 & 0 \end{bmatrix} \quad \rightarrow \begin{bmatrix} \pm c_2s_2(n) \\ \pm c_1s_1(n) \end{bmatrix}, \]
Does \( C(n) = B(n)A \) converge to one of the eight matrices?

\[
\begin{bmatrix}
\pm c_1 & 0 \\
0 & \pm c_2 \\
\end{bmatrix}
\text{ or }
\begin{bmatrix}
0 & \pm c_2 \\
\pm c_1 & 0 \\
\end{bmatrix}
\]

\textbf{Theorem 1:} If the sources \( s_i(n) \) are independent random variables, with symmetric probability density functions; and at most one is Gaussian, then

\[
\lim_{n \to \infty} E \{ C(n) \} = \begin{bmatrix}
\pm c_1 & 0 \\
0 & \pm c_2 \\
\end{bmatrix}
\text{ or }
\begin{bmatrix}
0 & \pm c_2 \\
\pm c_1 & 0 \\
\end{bmatrix}
\]

\[
\lim_{n \to \infty} E \{(C(n)-E\{C(\infty)\})^2\} = O(\mu)
\]
Observations

- No knowledge of the exact pdfs is required; only symmetry (and independence (?)).

\[
H(z_1, z_2) = \begin{bmatrix}
  z_1^2 - 1 & z_1 z_2 \\
  z_1 z_2 & z_2^2 - 1
\end{bmatrix}
\]

\[
+ \begin{bmatrix}
  0 & g_1(z_1)z_2 - g_2(z_2)z_1 \\
  -g_1(z_1)z_2 + g_2(z_2)z_1 & 0
\end{bmatrix}
\]

\[
g_i(z) = \alpha_i z^3 \quad \text{common choice}
\]

- Two or more Gaussian sources are NOT separable, in the sense that for ANY adaptive algorithm there is a continuum of limits instead of the 8 desirable ones.
Dependent Source Statistics

◆ If sources are dependent and the joint pdf is known, in principle we can construct adaptive algorithms that solve the source separation problem.

◆ We are interested in dependent sources for which it is not required knowledge of the pdfs.

All bivariate densities must satisfy the following quadratical symmetry

\[ f_{ij}(s_i, s_j) = f_{ij}(-s_i, s_j) = f_{ij}(s_i, -s_j) \]

\[
f(s_1, \ldots, s_L) = 0.99 \prod_{i=1}^{L} f_i(s_i) + 0.01 \prod_{i=1}^{L} g_i(s_i)
\]
General adaptive scheme

\[ \hat{S}(n) = B(n-1)X(n), \quad X(n) = AS(n) \]

\[ B(n) = B(n-1) - \mu H\left(\hat{S}(n)\right)B(n-1), \quad B(0) = I \]

\[ H(z_1, z_2) = \begin{bmatrix} h(z_1) & q(z_2, z_1) \\ q(z_1, z_2) & h(z_2) \end{bmatrix} \]

\[ \hat{S}(n) = C(n-1)S(n), \quad C(n) = B(n)A \]

\[ C(n) = C(n-1) - \mu H\left(\hat{S}(n)\right)C(n-1), \quad C(0) = A \]

\[ C(n) = C(n-1) - \mu H\left(C(n-1)S(n)\right)C(n-1) \]
From the theory of adaptive algorithms we know that an algorithm of the form

\[ C(n) = C(n-1) - \mu H(C(n-1)S(n))C(n-1) \]

converges in the mean \( \lim_{n \to \infty} E\{C(n)\} = C \), where \( C \) is an equilibrium matrix satisfying the equation

\[ C = C - \mu E \{ H(CS(n)) \} C \]

or equivalently \( E \{ H(CS(n)) \} = 0 \)
Since

\[
H(z_1, z_2) = \begin{bmatrix}
h(z_1) & q(z_2, z_1) \\
q(z_1, z_2) & h(z_2)
\end{bmatrix}
\]

relation \( E\{H(CS(n))\} = 0 \)
is equivalent to a system of four (in general nonlinear) equations

\[
E\{h(CS(n))\} = E\{q(CS(n))\} = 0
\]
in four unknowns (the four elements of matrix \( C \)) that can be solved to identify the equilibrium matrices.
If we want a specific matrix $C_0$ to become an equilibrium, then the elements of $H(Z)$ must satisfy

$$E \{ h(C_0 S(n)) \} = E \{ q(C_0 S(n)) \} = 0$$

If in particular we like the following eight matrices

$$C_0 = \begin{bmatrix} \pm c_1 & 0 \\ 0 & \pm c_2 \end{bmatrix}, \begin{bmatrix} 0 & \pm c_2 \\ \pm c_1 & 0 \end{bmatrix}$$

to become equilibriums, then

$$E \{ h(\pm c_i s_i) \} = E \{ q(\pm c_i s_i, \pm c_j s_j) \} = 0$$
Imposing symmetric behavior

For every trajectory converging to one limit we require existence of symmetric trajectories converging to the other seven limits with the same probability.

\[
H(z_1, z_2) = \begin{bmatrix}
    h(z_1) & q(z_2, z_1) \\
    q(z_1, z_2) & h(z_2)
\end{bmatrix}
\]

\[
h(-z) = h(z)
\]

\[
q(-z_1, z_2) = q(z_1, -z_2) = -q(z_1, z_2)
\]

\[
E \{ h(c_1 s_1) \} = E \{ h(c_2 s_2) \} = 0
\]

\[
E \{ q(c_1 s_1, c_2 s_2) \} = E \{ q(c_2 s_2, c_1 s_1) \} = 0 \text{ (for free)}
\]
**Necessary conditions**

1. \( \mathbf{H}(z_1, z_2) = \begin{bmatrix} h(z_1) & q(z_2, z_1) \\ q(z_1, z_2) & h(z_2) \end{bmatrix} \)

2. \( h(-z) = h(z) \)

3. \( q(-z_1, z_2) = q(z_1, -z_2) = -q(z_1, z_2) \)

4. \( E \{ h(c_1 s_1) \} = E \{ h(c_2 s_2) \} = 0 \) (existence of \( c_1, c_2 \))

\[
\mathbf{H}(z_1, z_2) = \begin{bmatrix} z_1^2 - 1 & z_1 z_2 + g(z_1) z_2 - g(z_2) z_1 \\ z_1 z_2 - g(z_1) z_2 + g(z_2) z_1 & z_2^2 - 1 \end{bmatrix}
\]
Theorem 2: If the sources $s_i(n)$ are random variables, with symmetric bivariate densities and no bivariate density is of the form

$$f_{ij}(s_i, s_j) = \beta(K_i s_i^2 + K_j s_j^2)$$

that is, no bivariate density exhibits either elliptical or hyperbolic symmetry (with respect to the two axis), then the generalized algorithm has exactly the same convergence properties for the dependent class, as the existing algorithm for the independent class.
Quadrantally symmetric bivariate pdfs
Example

Existing scheme

\[
H(z_1, z_2) = \begin{bmatrix}
    z_1^2 - 1 & z_1z_2 + g(z_1)z_2 - g(z_2)z_1 \\
    z_1z_2 - g(z_1)z_2 + g(z_2)z_1 & z_2^2 - 1
\end{bmatrix}
\]

Select

\[
H(z_1, z_2) = \begin{bmatrix}
    |z_1| - 1 & z_1z_2^2 \text{sgn}(z_2) \\
    z_2z_1^2 \text{sgn}(z_1) & |z_2| - 1
\end{bmatrix}
\]

There is no whitening involved!!!
\[ f(s_1, s_2) = 0.5 \frac{e^{-s_1^2/2}}{\sqrt{2\pi}} \frac{e^{-s_2^2/2\sigma^2}}{\sqrt{2\pi\sigma^2}} + 0.5 \frac{e^{-s_1^2/2a^2\sigma^2}}{\sqrt{2\pi a^2 \sigma^2}} \frac{e^{-s_2^2/2a^2}}{\sqrt{2\pi a^2}} \]

If \( \sigma \neq 1 \) the two sources are separable
If \( \sigma = 1 \) the two sources are not separable

\[ a = 1.5, \; \sigma = 0.8 \]
$a=1.5, \sigma = 0.8$
$a = 1.5, \sigma = 1$
Define a performance measure for the algorithmic class

\[ C(n) = C(n-1) - \mu H(C(n-1)S(n))C(n-1) \]

with \( H(z_1, z_2) \) satisfying the five necessary conditions.

For performance there are two important quantities:

- Rate of convergence
- Steady state estimation error power

Both quantities depend on \( \mu \).

Combine the two quantities to define a fair performance measure.
\[
\left\| C(n) - E\{C(\infty)\}\right\|^2 = \sum_{i,j} \left( C_{ij}(n) - E\{C_{ij}(\infty)\} \right)^2
\]
Adjust the step sizes $\mu$ so that the algorithms have the same steady state error power, then compare their convergence rates.
It is possible to define an analytic performance measure that can characterize an adaptive algorithm.

\[
\text{Efficacy} = \text{function}\left(h(z), q(z_1, z_2), f_{ij}(s_i, s_j)\right)
\]

The important properties of the Efficacy are the following

- When comparing Efficacies of two algorithms, it is equivalent to comparing the two algorithms fairly!!
- The optimum algorithm is the one that maximizes the Efficacy over \(h(z), q(z_1, z_2)\).
Optimum adaptive algorithms

When the bivariate pdfs are different the optimization problem is still open.

When the sources are independent with the same pdf \( f(z) \), then

\[
h(z_1) = a \left( z_1 l(z_1) - 1 \right)
\]

\[
l(z) = - \frac{f'(z)}{f(z)}
\]

\[
q(z_1, z_2) = bz_1 l(z_2) + cz_2 l(z_1)
\]

where \( a, b, c \), proper constants

Existing scheme

\[
h(z_1) = z_1^2 - 1,
\]

\[
q(z_1, z_2) = z_1 z_2 + (z_1 g(z_2) - z_2 g(z_1))
\]

Maximize Efficacy with respect to \( g(z) \)

\[
q(z_1, z_2) = z_1 z_2 + d \left( z_1 l(z_2) - z_2 l(z_1) \right)
\]
We have presented a rich class of adaptive algorithms that can solve the blind source separation problem for dependent sources with symmetries.

We have identified the sources that cannot be separated with the specific combination of source statistics and algorithmic model.

We have proposed an analytic performance measure that can be optimized to yield the fastest converging algorithm in the equi-distributed source case.
Questions please?

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