

CS415 Compilers
Syntax Analysis
Bottom-up Parsing

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Parsing (Syntax Analysis)

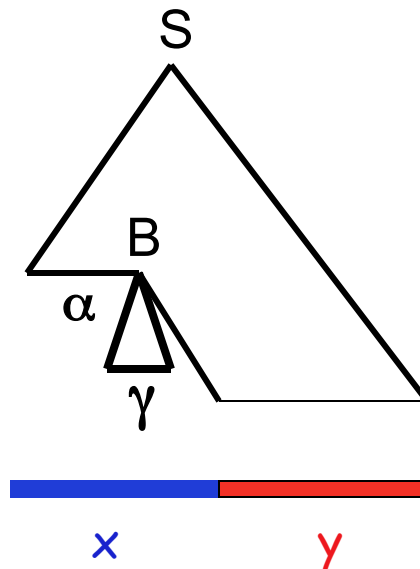
EAC Chapters 3.4

LR(1), operator precedence

1 input symbol lookahead
 construct rightmost derivation (backwards)
 input: read left-to-right

$$S \Rightarrow_{rm}^* \alpha(B)y \Rightarrow_{rm} \alpha(\gamma)y \Rightarrow_{rm}^* x y$$

rule $B ::= \gamma$



Shift reduce parsers are easily built and easily understood

A shift-reduce parser has just four actions

- **Shift** — next word is shifted onto the stack
- **Reduce** — right end of handle is at top of stack
Locate left end of handle within the stack
Pop handle off stack & push appropriate *lhs*
- **Accept** — stop parsing & report success
- **Error** — call an error reporting/recovery routine

Accept & Error are simple

Shift is just a push and a call to the scanner

Reduce takes $|rhs|$ pops & 1 push

If handle-finding requires state, put it in the stack \Rightarrow 2x work

Handle finding is key

- handle is on stack
 - finite set of handles
- \Rightarrow use a DFA !

To be a handle, a substring of a sentential form γ must have two properties:

- It must match the right hand side β of some rule $A \rightarrow \beta$
- There must be some rightmost derivation from the goal symbol that produces the sentential form γ with $A \rightarrow \beta$ as the last production applied
- Simply looking for right hand sides that match strings is not good enough
 - There could be shift or reduce conflicts

Stack	Input	Handle	Action
\$	<u>id</u> - <u>num</u> * <u>id</u>	<i>none</i>	shift
\$ <u>id</u>	- <u>num</u> * <u>id</u>		

1. Shift until the top of the stack is the right end of a handle
2. Find the left end of the handle & reduce

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\$ <i>Factor</i>	- <u>num</u> * <u>id</u>	7,1	red. 7
\$ <i>Term</i>	- <u>num</u> * <u>id</u>	4,1	red. 4
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\$ <i>Expr</i> - <i>Term</i>		3,3	red. 3
\$ <i>Expr</i>		1,1	red. 1
\$ <i>Goal</i>		<i>none</i>	accept

5 shifts +
9 reduces +
1 accept

1. Shift until the top of the stack is the right end of a handle
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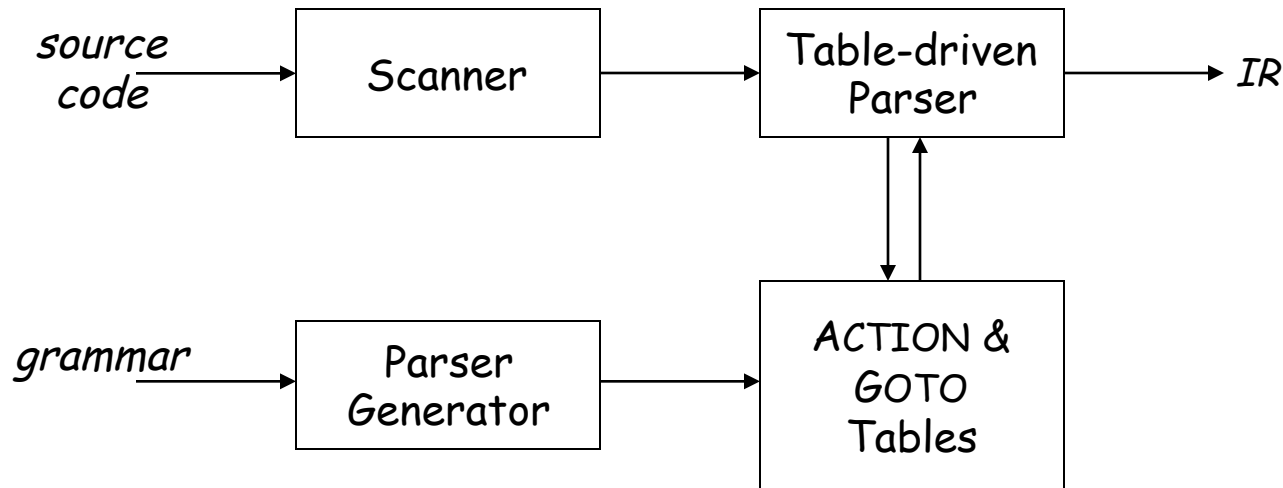
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\$ <u>Goal</u>		none	accept

shift here

reduce here

1. Shift until the top of the stack is the right end of a handle
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A table-driven LR(1) parser looks like



Tables can be built by hand

However, this is a perfect task to automate

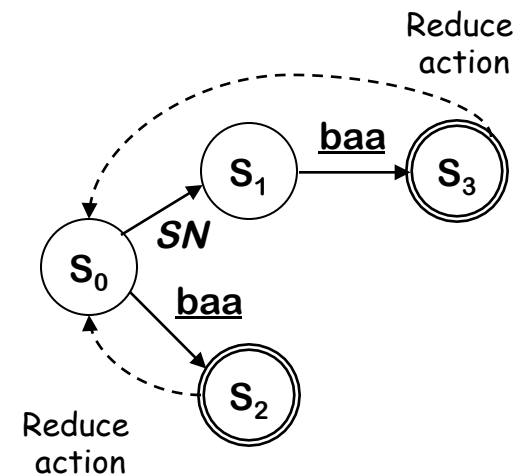
```
stack.push(INVALID); stack.push(s0);
not_found = true;
token = scanner.next_token();
do while (not_found) {
    s = stack.top();
    if ( ACTION[s,token] == "reduce A→β" ) then {
        stack.popnum(2*|β|); // pop 2*|β| symbols
        s = stack.top();
        stack.push(A);
        stack.push(GOTO[s,A]);
    }
    else if ( ACTION[s,token] == "shift si" ) then {
        stack.push(token); stack.push(si);
        token ← scanner.next_token();
    }
    else if ( ACTION[s,token] == "accept"
              & token == EOF )
        then not_found = false;
    else report a syntax error and recover;
}
report success;
```

The skeleton parser

- uses ACTION & GOTO tables
- does |words| shifts
- does |derivation| reductions
- does 1 accept
- detects errors by failure of 3 other cases

How does this LR(1) stuff work?

- Unambiguous grammar \Rightarrow unique rightmost derivation
- Keep upper fringe on a stack
 - \rightarrow All active handles include top of stack (TOS)
 - \rightarrow Shift inputs until TOS is right end of a handle
- Language of handles is regular (finite)
 - \rightarrow Build a handle-recognizing DFA
 - \rightarrow ACTION & GOTO tables encode the DFA
- To match subterm, invoke subterm DFA & leave old DFA's state on stack
- Final state in DFA \Rightarrow a *reduce* action
 - \rightarrow New state is $GOTO[\text{state at TOS (after pop)}, \text{lhs}]$
 - \rightarrow For *SN*, this takes the DFA to s_1

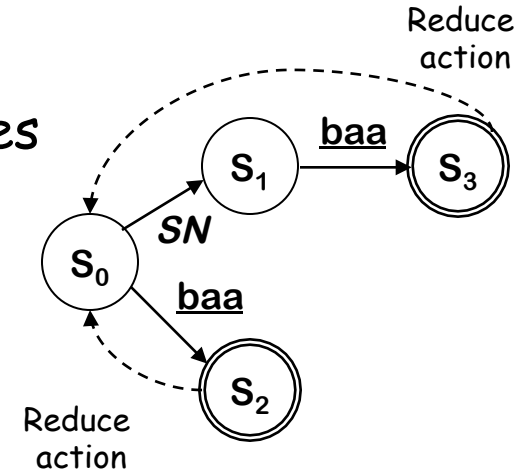


Control DFA for *SN*

To make a parser for $L(G)$, need a set of tables

The grammar

1	<i>Goal</i>	→	SheepNoise
2	<i>SheepNoise</i>	→	SheepNoise <u>baa</u>
3			<u>baa</u>



The tables

ACTION		
State	EOF	<u>baa</u>
0	—	shift 2
1	accept	shift 3
2	reduce 3	reduce 3
3	reduce 2	reduce 2

Control DFA for SN

GOTO	
State	<i>SheepNoise</i>
0	1
1	-
2	-
3	-

How do we generate the ACTION and GOTO tables?

- Use the grammar to build a model of the DFA
- Use the model to build ACTION & GOTO tables
- If construction succeeds, the grammar is LR(1)

*Terminal or
non-terminal*

The Big Picture

- Model the state of the parser
- Use two functions $goto(s, X)$ and $closure(s)$
 - $goto()$ is analogous to $move()$ in the subset construction
 - $closure()$ adds information to round out a state
- Build up the states and transition functions of the DFA
- Use this information to fill in the ACTION and GOTO tables

The LR(1) table construction algorithm uses LR(1) items to represent valid configurations of an LR(1) parser

An LR(k) item is a pair $[P, \delta]$, where

P is a production $A \rightarrow \beta$ with a \cdot at some position in the *rhs*

δ is a lookahead string of length $\leq k$ (words or EOF)

The \cdot in an item indicates the position of the top of the stack

LR(1):

$[A \rightarrow \cdot \beta \gamma, \underline{a}]$ means that the input seen so far is consistent with the use of $A \rightarrow \beta \gamma$ immediately after the symbol on top of the stack

$[A \rightarrow \beta \cdot \gamma, \underline{a}]$ means that the input seen so far is consistent with the use of $A \rightarrow \beta \gamma$ at this point in the parse, and that the parser has already recognized β .

$[A \rightarrow \beta \gamma \cdot, \underline{a}]$ means that the parser has seen $\beta \gamma$, and that a lookahead symbol of \underline{a} is consistent with reducing to A .

The production $A \rightarrow \beta$, where $\beta = B_1 B_2 B_3$ with lookahead \underline{a} , can give rise to 4 items

$$[A \rightarrow \cdot B_1 B_2 B_3, \underline{a}], [A \rightarrow B_1 \cdot B_2 B_3, \underline{a}], [A \rightarrow B_1 B_2 \cdot B_3, \underline{a}], \text{ \& } [A \rightarrow B_1 B_2 B_3 \cdot, \underline{a}]$$

The set of LR(1) items for a grammar is **finite**

What's the point of all these lookahead symbols?

- Carry them along to choose the correct reduction, *if there is a choice*
 - Lookaheads are bookkeeping, unless item has \cdot at right end
 - Has no direct use in $[A \rightarrow \beta \cdot \gamma, \underline{a}]$
 - In $[A \rightarrow \beta \cdot, \underline{a}]$, a lookahead of \underline{a} implies a reduction by $A \rightarrow \beta$
 - For $\{ [A \rightarrow \beta \cdot, \underline{a}], [B \rightarrow \gamma \cdot \delta, \underline{b}] \}$, $\underline{a} \Rightarrow$ *reduce* to A ; $\text{FIRST}(\delta) \Rightarrow$ *shift*
- ⇒ Limited right context is enough to pick the actions (unique, i.e., deterministic choice)

High-level overview

1 Build the **canonical collection of sets of LR(1) Items, I** a Begin in an appropriate state, s_0

- ◆ Assume: $S' \rightarrow S$, and S' is unique start symbol that does not occur on any RHS of a production (extended CFG - ECFG)

- ◆ $[S' \rightarrow \cdot S, \underline{\text{EOF}}]$, along with any equivalent items

- ◆ Derive equivalent items as $\text{closure}(s_0)$

b Repeatedly compute, for each s_k , and each X , $\text{goto}(s_k, X)$

- ◆ If the set is not already in the collection, add it

- ◆ Record all the transitions created by $\text{goto}()$

This eventually reaches a fixed point

2 Fill in the table from the collection of sets of LR(1) items

The canonical collection completely encodes the transition diagram for the handle-finding DFA

$Closure(s)$ adds all the items implied by items already in s

- Any item $[A \rightarrow \beta \cdot B \delta, \underline{a}]$ implies $[B \rightarrow \cdot \tau, \underline{x}]$ for each production with B on the *lhs*, and each $x \in FIRST(\delta \underline{a})$

The algorithm

```

Closure( s )
  while ( s is still changing )
     $\forall$  items  $[A \rightarrow \beta \cdot B \delta, \underline{a}] \in s$ 
       $\forall$  productions  $B \rightarrow \tau \in P$ 
         $\forall \underline{b} \in FIRST(\delta \underline{a})$  //  $\delta$  might be  $\epsilon$ 
          if  $[B \rightarrow \cdot \tau, \underline{b}] \notin s$ 
            then add  $[B \rightarrow \cdot \tau, \underline{b}]$  to  $s$ 
  
```

- Classic fixed-point method
 - Halts because $s \subset ITEMS$
 - Worklist version is faster
- Closure “fills out” a state*

$Goto(s, x)$ computes the state that the parser would reach if it recognized an x while in state s

- $Goto(\{ [A \rightarrow \beta \cdot X \delta, \underline{a}] \}, X)$ produces $[A \rightarrow \beta X \cdot \delta, \underline{a}]$ (*easy part*)
- Should also includes $closure([A \rightarrow \beta X \cdot \delta, \underline{a}])$ (*fill out the state*)

The algorithm

```

Goto(s, X)
  new ← ∅
  ∀ items [A → β · X δ, a] ∈ s
    new ← new ∪ [A → β X · δ, a]
  return closure(new)

```

- Not a fixed-point method!
 - Straightforward computation
 - Uses $closure()$
- Goto() moves forward*

Start from $s_0 = \text{closure}([S' \rightarrow S, \underline{\text{EOF}}])$

Repeatedly construct new states, until all are found

The algorithm

```

 $cc_0 \leftarrow \text{closure}([S' \rightarrow \bullet S, \underline{\text{EOF}}])$ 
 $CC \leftarrow \{ cc_0 \}$ 
while (new sets are still being added to  $CC$ )
  for each unmarked set  $cc_j \in CC$ 
    mark  $cc_j$  as processed
    for each  $x$  following a  $\bullet$  in an item in  $cc_j$ 
       $temp \leftarrow \text{goto}(cc_j, x)$ 
      if  $temp \notin CC$ 
        then  $CC \leftarrow CC \cup \{temp\}$ 
      record transitions from  $cc_j$  to  $temp$  on  $x$ 

```

- Fixed-point computation
(worklist version)
- Loop adds to CC
- $CC \subseteq 2^{\text{ITEMS}}$,
so CC is finite

We will use this grammar again:

Goal \rightarrow SheepNoise

SheepNoise \rightarrow SheepNoise baa

| baa

Initial step builds the item $[Goal \rightarrow \cdot SheepNoise, EOF]$
and takes its *closure*()

NOTE: this is the left-recursive SheepNoise; EaC shows the right-recursive version.

Closure($[Goal \rightarrow \cdot SheepNoise, EOF]$)

<i>Item</i>	<i>From</i>
$[Goal \rightarrow \cdot SheepNoise, \underline{EOF}]$	Original item
$[SheepNoise \rightarrow \cdot SheepNoise \underline{baa}, \underline{EOF}]$	1, δ_a is <u>EOF</u>
$[SheepNoise \rightarrow \cdot \underline{baa}, \underline{EOF}]$	1, δ_a is <u>EOF</u>
$[SheepNoise \rightarrow \cdot SheepNoise \underline{baa}, \underline{baa}]$	2, δ_a is <u>baa</u> <u>EOF</u>
$[SheepNoise \rightarrow \cdot \underline{baa}, \underline{baa}]$	2, δ_a is <u>baa</u> <u>EOF</u>

So, cc_0 is

{ $[Goal \rightarrow \cdot SheepNoise, \underline{EOF}]$, $[SheepNoise \rightarrow \cdot SheepNoise \underline{baa}, \underline{EOF}]$,
 $[SheepNoise \rightarrow \cdot \underline{baa}, \underline{EOF}]$, $[SheepNoise \rightarrow \cdot SheepNoise \underline{baa}, \underline{baa}]$,
 $[SheepNoise \rightarrow \cdot \underline{baa}, \underline{baa}]$ }

cc_0 is $\{ [Goal \rightarrow \cdot SheepNoise, EOF], [SheepNoise \rightarrow \cdot SheepNoise \underline{baa}, EOF], [SheepNoise \rightarrow \cdot \underline{baa}, EOF], [SheepNoise \rightarrow \cdot SheepNoise \underline{baa}, \underline{baa}], [SheepNoise \rightarrow \cdot \underline{baa}, \underline{baa}] \}$

$Goto(cc_0, \underline{baa})$

- Loop produces

<i>Item</i>	<i>From</i>
$[SheepNoise \rightarrow \underline{baa} \cdot, EOF]$	Item 3 in cc_0
$[SheepNoise \rightarrow \underline{baa} \cdot, \underline{baa}]$	Item 5 in cc_0

- Closure adds nothing since \cdot is at end of *rhs* in each item

In the construction, this produces cc_2

$\{ [SheepNoise \rightarrow \underline{baa} \cdot, \{EOF, \underline{baa}\}] \}$

New, but obvious, notation for two distinct items

$[SheepNoise \rightarrow \underline{baa} \cdot, EOF]$ &
 $[SheepNoise \rightarrow \underline{baa} \cdot, \underline{baa}]$

Starts with cc_0

$cc_0 : \{ [Goal \rightarrow \cdot SheepNoise, \underline{EOF}], [SheepNoise \rightarrow \cdot SheepNoise \underline{baa}, \underline{EOF}],$
 $[SheepNoise \rightarrow \cdot \underline{baa}, \underline{EOF}], [SheepNoise \rightarrow \cdot SheepNoise \underline{baa}, \underline{baa}],$
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Starts with cc_0

$$cc_0 : \{ [Goal \rightarrow \cdot SheepNoise, \underline{EOF}], [SheepNoise \rightarrow \cdot SheepNoise \underline{baa}, \underline{EOF}], \\ [SheepNoise \rightarrow \cdot \underline{baa}, \underline{EOF}], [SheepNoise \rightarrow \cdot SheepNoise \underline{baa}, \underline{baa}], \\ [SheepNoise \rightarrow \cdot \underline{baa}, \underline{baa}] \}$$

Iteration 1 computes

$$cc_1 = Goto(cc_0, SheepNoise) =$$

$$\{ [Goal \rightarrow SheepNoise \cdot, \underline{EOF}], [SheepNoise \rightarrow SheepNoise \cdot \underline{baa}, \underline{EOF}], \\ [SheepNoise \rightarrow SheepNoise \cdot \underline{baa}, \underline{baa}] \}$$

$$cc_2 = Goto(cc_0, \underline{baa}) = \{ [SheepNoise \rightarrow \underline{baa} \cdot, \underline{EOF}], \\ [SheepNoise \rightarrow \underline{baa} \cdot, \underline{baa}] \}$$

Starts with cc_0

$$cc_0 : \{ [Goal \rightarrow \cdot SheepNoise, \underline{EOF}], [SheepNoise \rightarrow \cdot SheepNoise \underline{baa}, \underline{EOF}], \\ [SheepNoise \rightarrow \cdot \underline{baa}, \underline{EOF}], [SheepNoise \rightarrow \cdot SheepNoise \underline{baa}, \underline{baa}], \\ [SheepNoise \rightarrow \cdot \underline{baa}, \underline{baa}] \}$$

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$$cc_2 = Goto(cc_0, \underline{baa}) = \{ [SheepNoise \rightarrow \underline{baa} \cdot, \underline{EOF}], \\ [SheepNoise \rightarrow \underline{baa} \cdot, \underline{baa}] \}$$

Iteration 2 computes

$$cc_3 = Goto(cc_1, \underline{baa}) = \{ [SheepNoise \rightarrow SheepNoise \underline{baa} \cdot, \underline{EOF}], \\ [SheepNoise \rightarrow SheepNoise \underline{baa} \cdot, \underline{baa}] \}$$

Starts with cc_0

$$cc_0 : \{ [Goal \rightarrow \cdot SheepNoise, EOF], [SheepNoise \rightarrow \cdot SheepNoise \underline{baa}, EOF], \\ [SheepNoise \rightarrow \cdot \underline{baa}, EOF], [SheepNoise \rightarrow \cdot SheepNoise \underline{baa}, \underline{baa}], \\ [SheepNoise \rightarrow \cdot \underline{baa}, \underline{baa}] \}$$

Iteration 1 computes

$$cc_1 = Goto(cc_0, SheepNoise) = \\ \{ [Goal \rightarrow SheepNoise \cdot, EOF], [SheepNoise \rightarrow SheepNoise \cdot \underline{baa}, EOF], \\ [SheepNoise \rightarrow SheepNoise \cdot \underline{baa}, \underline{baa}] \}$$

$$cc_2 = Goto(cc_0, \underline{baa}) = \{ [SheepNoise \rightarrow \underline{baa} \cdot, EOF], \\ [SheepNoise \rightarrow \underline{baa} \cdot, \underline{baa}] \}$$

Iteration 2 computes

$$cc_3 = Goto(cc_1, \underline{baa}) = \{ [SheepNoise \rightarrow SheepNoise \underline{baa} \cdot, EOF], \\ [SheepNoise \rightarrow SheepNoise \underline{baa} \cdot, \underline{baa}] \}$$

Nothing more to compute, since \cdot is at the end of every item in cc_3 .

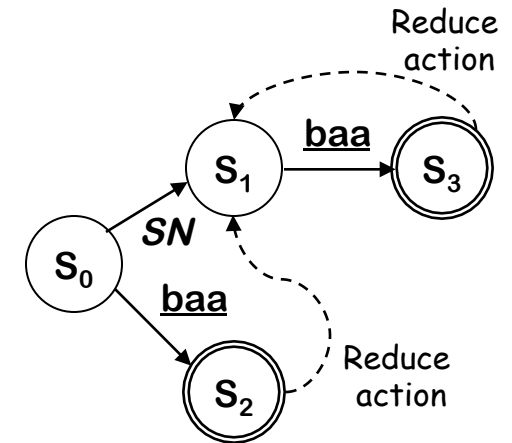
Canonical LR(1) Collection:

$$S_0 : \{ [Goal \rightarrow \cdot SheepNoise, \underline{EOF}], [SheepNoise \rightarrow \cdot SheepNoise \underline{baa}, \underline{EOF}], \\ [SheepNoise \rightarrow \cdot \underline{baa}, \underline{EOF}], [SheepNoise \rightarrow \cdot SheepNoise \underline{baa}, \underline{baa}], \\ [SheepNoise \rightarrow \cdot \underline{baa}, \underline{baa}] \}$$

Iteration 1 computes

$$S_1 = Goto(S_0, SheepNoise) =$$

$$\{ [Goal \rightarrow SheepNoise \cdot, \underline{EOF}], [SheepNoise \rightarrow SheepNoise \cdot \underline{baa}, \underline{EOF}], \\ [SheepNoise \rightarrow SheepNoise \cdot \underline{baa}, \underline{baa}] \}$$

$$S_2 = Goto(S_0, \underline{baa}) = \{ [SheepNoise \rightarrow \underline{baa} \cdot, \underline{EOF}], \\ [SheepNoise \rightarrow \underline{baa} \cdot, \underline{baa}] \}$$


Iteration 2 computes

$$S_3 = Goto(S_1, \underline{baa}) = \{ [SheepNoise \rightarrow SheepNoise \underline{baa} \cdot, \underline{EOF}], \\ [SheepNoise \rightarrow SheepNoise \underline{baa} \cdot, \underline{baa}] \}$$

To make a parser for $L(G)$, need a set of tables

The grammar

1	<i>Goal</i>	→	SheepNoise
2	<i>SheepNoise</i>	→	SheepNoise <u>baa</u>
3			<u>baa</u>

Remember, this is the left-recursive SheepNoise; EaC shows the right-recursive version.

The tables

ACTION		
State	EOF	<u>baa</u>
0	—	shift 2
1	accept	shift 3
2	reduce 3	reduce 3
3	reduce 2	reduce 2

GOTO	
State	<i>SheepNoise</i>
0	1
1	-
2	-
3	-

The string “baa”

Stack	Input	Action
\$ s_0	<u>baa</u> <u>EOF</u>	shift 2

1	<i>Goal</i>	→	SheepNoise
2	<i>SheepNoise</i>	→	SheepNoise <u>baa</u>
3			<u>baa</u>

ACTION		
State	EOF	<u>baa</u>
0	—	shift 2
1	accept	shift 3
2	reduce 3	reduce 3
3	reduce 2	reduce 2

GOTO	
State	<i>SheepNoise</i>
0	1
1	-
2	-
3	-

The string “baa”

Stack	Input	Action
\$ s ₀	<u>baa</u> <u>EOF</u>	shift 2
\$ s ₀ <u>baa</u> s ₂	<u>EOF</u>	reduce 3

1	<i>Goal</i>	→	SheepNoise
2	<i>SheepNoise</i>	→	SheepNoise <u>baa</u>
3			<u>baa</u>

ACTION		
State	EOF	<u>baa</u>
0	—	shift 2
1	accept	shift 3
2	reduce 3	reduce 3
3	reduce 2	reduce 2

GOTO	
State	<i>SheepNoise</i>
0	1
1	-
2	-
3	-

The string “baa”

Stack	Input	Action
\$ s_0	<u>baa</u> <u>EOF</u>	shift 2
\$ s_0 <u>baa</u> s_2	<u>EOF</u>	reduce 3
\$ s_0 <i>SN</i> s_1	<u>EOF</u>	

1	<i>Goal</i>	→	SheepNoise
2	<i>SheepNoise</i>	→	SheepNoise <u>baa</u>
3			<u>baa</u>

ACTION		
State	EOF	<u>baa</u>
0	—	shift 2
1	accept	shift 3
2	reduce 3	reduce 3
3	reduce 2	reduce 2

GOTO	
State	<i>SheepNoise</i>
0	1
1	-
2	-
3	-

The string “baa”

Stack	Input	Action
\$ s_0	<u>baa</u> <u>EOF</u>	shift 2
\$ s_0 <u>baa</u> s_2	<u>EOF</u>	reduce 3
\$ s_0 <i>SN</i> s_1	<u>EOF</u>	accept

1	<i>Goal</i>	→	SheepNoise
2	<i>SheepNoise</i>	→	SheepNoise <u>baa</u>
3			<u>baa</u>

ACTION		
State	EOF	<u>baa</u>
0	—	shift 2
1	accept	shift 3
2	reduce 3	reduce 3
3	reduce 2	reduce 2

GOTO	
State	<i>SheepNoise</i>
0	1
1	-
2	-
3	-

The string “baa baa ”

Stack	Input	Action
\$ s ₀	<u>baa</u> <u>baa</u> <u>EOF</u>	shift 2
\$ s ₀ <u>baa</u> s ₂	<u>baa</u> <u>EOF</u>	

1	<i>Goal</i>	→	SheepNoise
2	<i>SheepNoise</i>	→	SheepNoise <u>baa</u>
3			<u>baa</u>

ACTION		
State	EOF	<u>baa</u>
0	—	shift 2
1	accept	shift 3
2	reduce 3	reduce 3
3	reduce 2	reduce 2

GOTO	
State	<i>SheepNoise</i>
0	1
1	-
2	-
3	-

The string “baa baa ”

Stack	Input	Action
\$ s ₀	<u>baa</u> <u>baa</u> <u>EOF</u>	shift 2
\$ s ₀ <u>baa</u> s ₂	<u>baa</u> <u>EOF</u>	reduce 3
\$ s ₀ SN s ₁	<u>baa</u> <u>EOF</u>	

1	<i>Goal</i>	→	SheepNoise
2	<i>SheepNoise</i>	→	SheepNoise <u>baa</u>
3			<u>baa</u>

ACTION		
State	EOF	<u>baa</u>
0	—	shift 2
1	accept	shift 3
2	reduce 3	reduce 3
3	reduce 2	reduce 2

GOTO	
State	<i>SheepNoise</i>
0	1
1	-
2	-
3	-

The string “baa baa ”

Stack	Input	Action
\$ s ₀	<u>baa</u> <u>baa</u> <u>EOF</u>	shift 2
\$ s ₀ <u>baa</u> s ₂	<u>baa</u> <u>EOF</u>	reduce 3
\$ s ₀ SN s ₁	<u>baa</u> <u>EOF</u>	shift 3
\$ s ₀ SN s ₁ <u>baa</u> s ₃	<u>EOF</u>	

1	<i>Goal</i>	→	SheepNoise
2	<i>SheepNoise</i>	→	SheepNoise <u>baa</u>
3			<u>baa</u>

ACTION		
State	EOF	<u>baa</u>
0	—	shift 2
1	accept	shift 3
2	reduce 3	reduce 3
3	reduce 2	reduce 2

GOTO	
State	<i>SheepNoise</i>
0	1
1	-
2	-
3	-

The string “baa baa ”

Stack	Input	Action
\$ s ₀	<u>baa</u> <u>baa</u> <u>EOF</u>	shift 2
\$ s ₀ <u>baa</u> s ₂	<u>baa</u> <u>EOF</u>	reduce 3
\$ s ₀ SN s ₁	<u>baa</u> <u>EOF</u>	shift 3
\$ s ₀ SN s ₁ <u>baa</u> s ₃	<u>EOF</u>	reduce 2
\$ s ₀ SN s ₁	<u>EOF</u>	accept

1	Goal	→	SheepNoise
2	SheepNoise	→	SheepNoise <u>baa</u>
3			<u>baa</u>

ACTION		
State	EOF	<u>baa</u>
0	—	shift 2
1	accept	shift 3
2	reduce 3	reduce 3
3	reduce 2	reduce 2

GOTO	
State	SheepNoise
0	1
1	-
2	-
3	-

Wrap-up Syntax Analysis

Start Context-Sensitive Analysis

Read EaC: Chapters 4.1 - 4.3